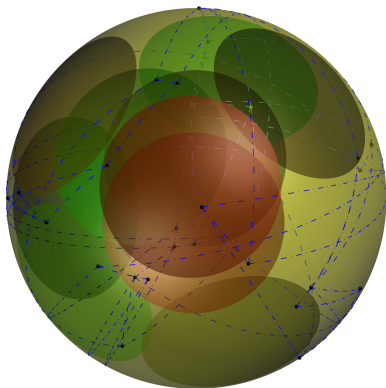


# From Weak to Strong LP Gaps for all CSPs



Mrinalkanti Ghosh

joint work with:  
Madhur Tulsiani

# MAX $k$ -CSP

---

- $n$  variables
- $m$  constraints

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- $n$  variables taking boolean values.
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- Satisfy as many as possible.

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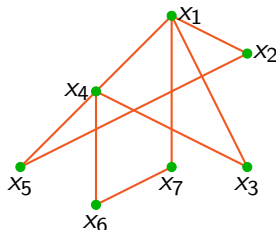
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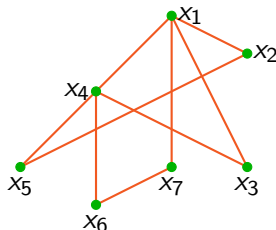
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Approximation Problem: Approximate the *fraction* of constraints simultaneously satisfiable.

# MAX k-CSP

- $n$  variables taking values in some finite domains.
- $m$  constraints: each is a non-negative  $k$ -ary function.
- Satisfy as many as possible.

## Max-3-SAT

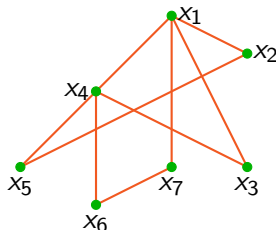
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# CSPs and Relaxations

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MAX k-CSP ( $f$ ): for  $i$ -th constraint, let  $S_{C_i} := (x_{i_1}, \dots, x_{i_k})$ . Then:

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$$\forall C \in \Phi, i \in S_C, \\ b \in \{0, 1\}$$

$$\sum_{b \in \{0,1\}} x_{(i, b)} = 1$$

$$\forall i \in [n]$$

$$x_{(S, \alpha)} \geq 0$$

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# Extended Formulation and Sherali-Adams Relaxation

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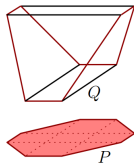


Image from  
[Fiorini-Rothvoss-Tiwari-11]

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- Optimize objective  $\langle w_\Phi, x \rangle$  (depending on  $\Phi$ ) over  $P$ .
- Introduce additional variables  $y$ .  
Optimize over polytope  
$$P = \{x \mid \exists y \quad Ex + Fy = g, y \geq 0\}.$$
  
Size equals  
 $\#variables + \#constraints.$

# Extended Formulation and Sherali-Adams Relaxation

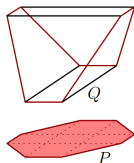


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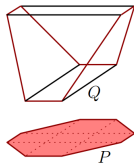


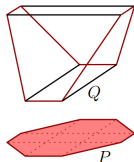
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- **Variables:**  $x_{(S,\alpha)}$ ,  $|S| \leq t$ ,  $\alpha \in \{0,1\}^S$ .



# Extended Formulation and Sherali-Adams Relaxation

EF:



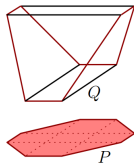
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- Feasible point in  $SA(t)$ : Family  $\{\mathcal{D}_S\}_{|S| \leq t}$  of **consistent distribution** with  $\mathcal{D}_S$  a distribution on  $\{0, 1\}^S$ .

# Extended Formulation and Sherali-Adams Relaxation

EF:



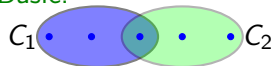
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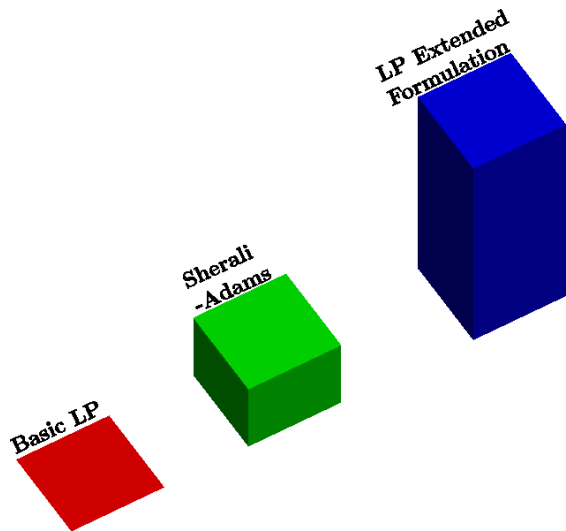
Basic:



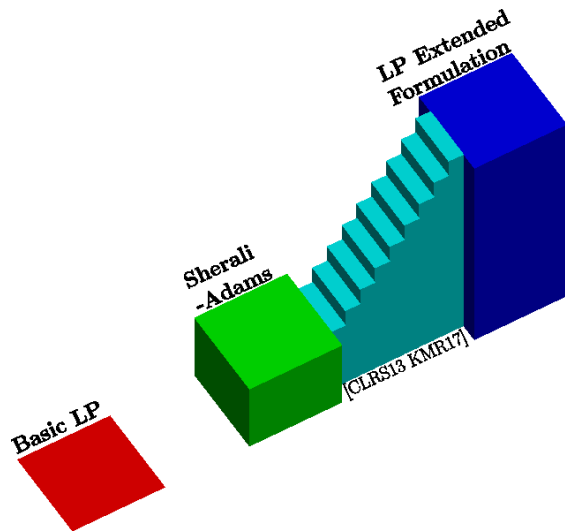
- Feasible point in  $SA(t)$ : Family  $\{\mathcal{D}_S\}_{|S| \leq t}$  of **consistent distribution** with  $\mathcal{D}_S$  a distribution on  $\{0, 1\}^S$ .
- Similarly, for Basic LP solution.

# Result

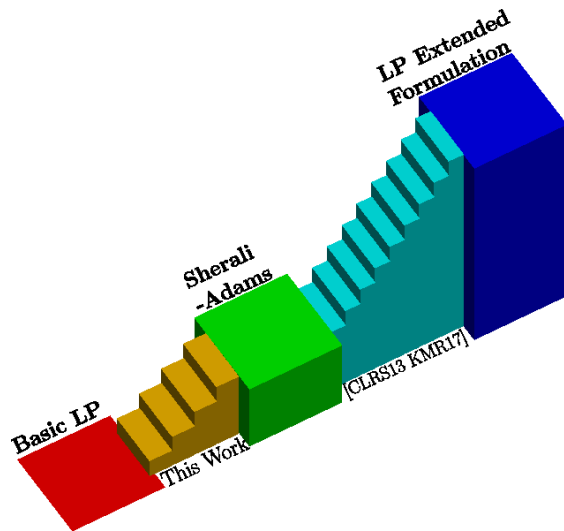
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# Result

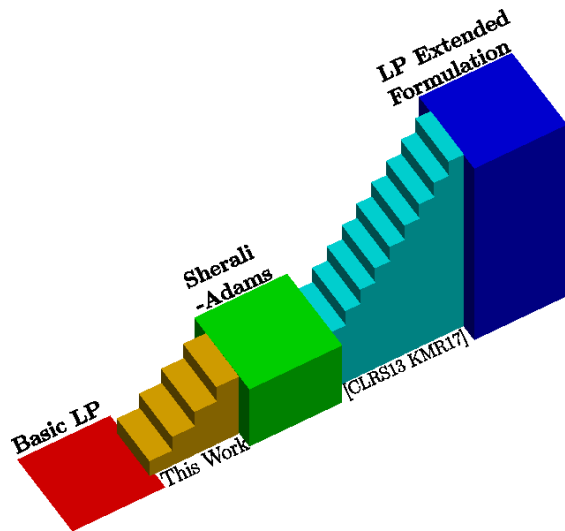


# Result



**Main Theorem:** For all CSPs, if Basic LP has integrality gap of  $(c, s)$  then for all  $\varepsilon > 0$ , there exist large enough instance(s) with integrality gap of  $(c - \varepsilon, s + \varepsilon)$  for  $SA(\tilde{O}_\varepsilon(\log n))$ .

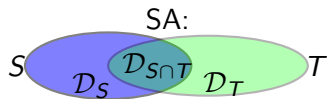
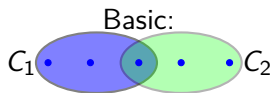
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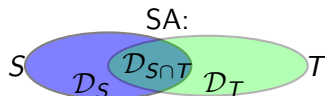
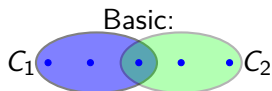
With [Kothari-Meka-Raghavendra-17]: For *all* CSPs, if Basic LP has  $(c, s)$  gap, then so does any LP Extended Formulation of size  $n^{\tilde{O}(\log n)}$ .

Ignoring  $\varepsilon$  losses.

# Hard Instance



# Hard Instance



Use the hard instance  $\Phi_0$  of the basic relaxation as **template** to build the new hard instance on  **$n$  variables** and  **$m = \Delta \cdot n$  constraints**.



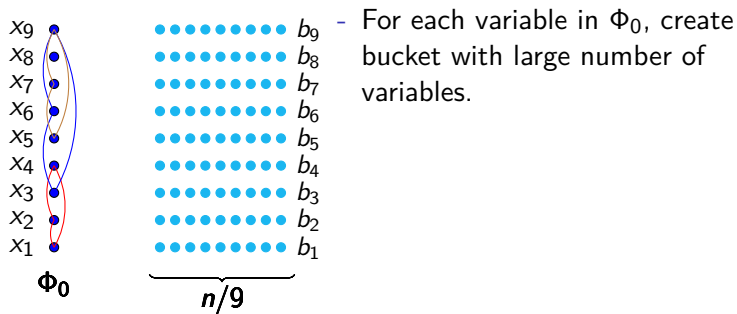
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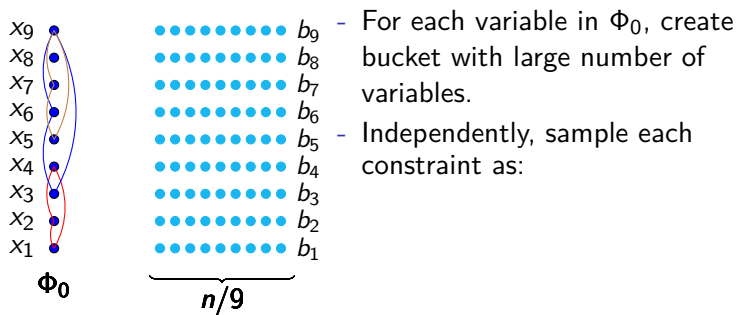
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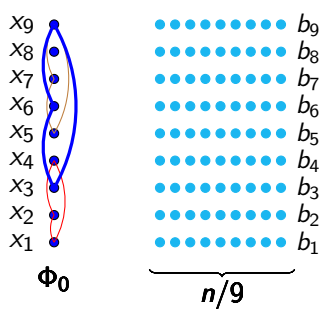
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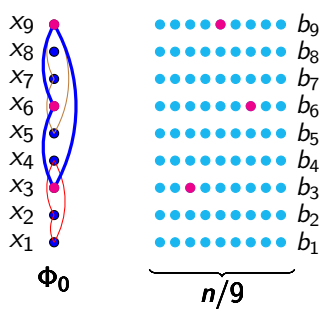
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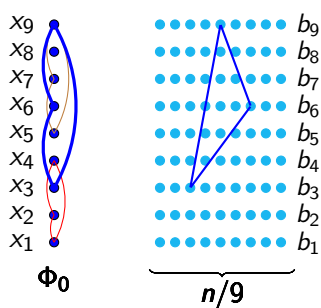
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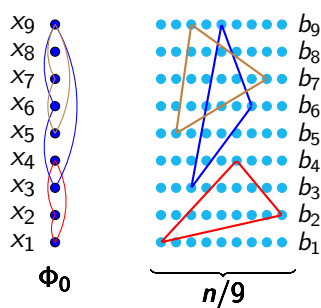
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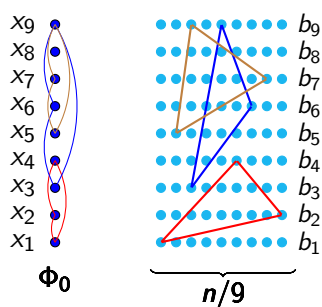


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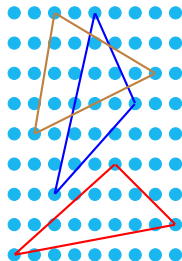
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# Overview - Completeness

Instance:

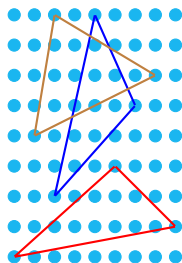


Consistent Distributions:



# Overview - Completeness

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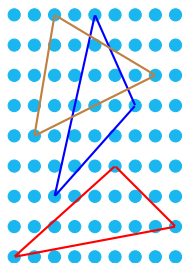
Consistent Distributions:



Step 2: Construction of consistent distribution – Conditioning and propagating.

# Overview - Completeness

Instance:



Consistent Distributions:



- Step 1: Consistent Low-Diameter Decompositions.
- Step 2: Construction of consistent distribution – Conditioning and propagating.

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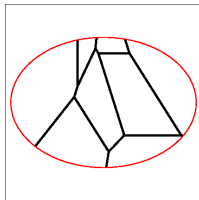


Figure:  $S \subset T$

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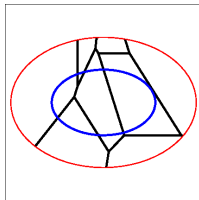


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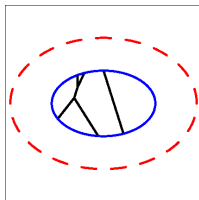


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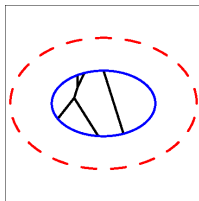


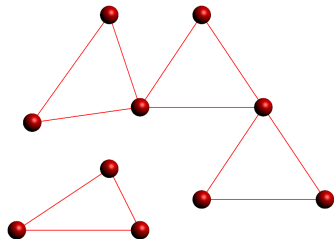
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## Step 2: Conditioning and Propagation

Assume:  $c = 1$

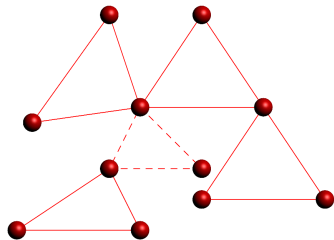


Construction of  $\mathcal{D}_S$ :

- Sample a partition  $\mathcal{P}$  of  $S$  from  $\mathcal{C}_S$ .

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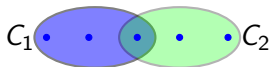
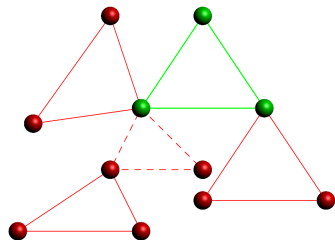


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Assume:  $c = 1$

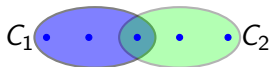
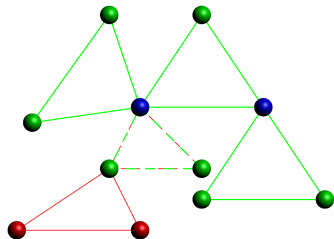


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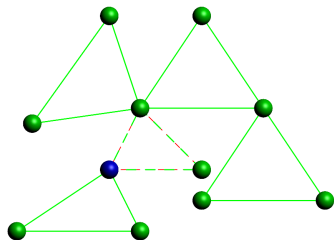


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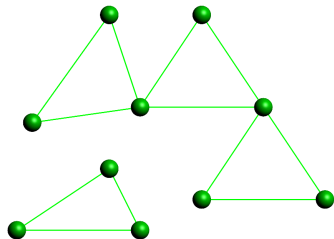
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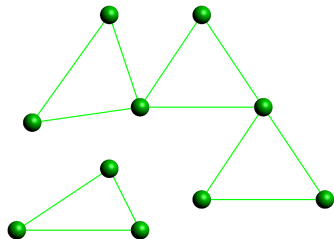
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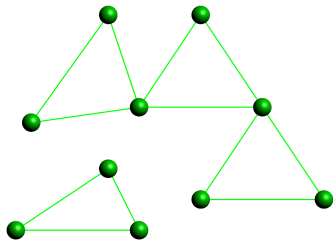
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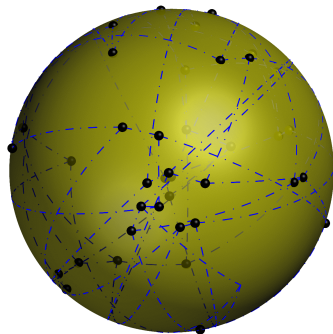
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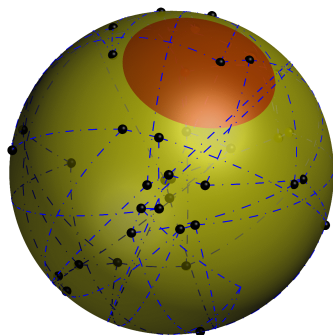


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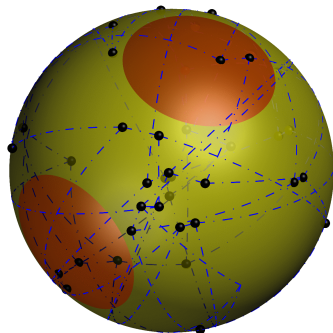
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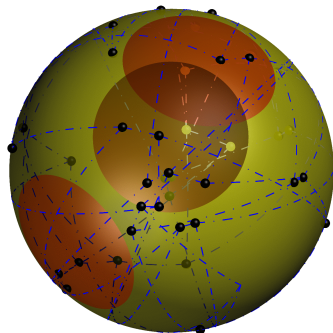


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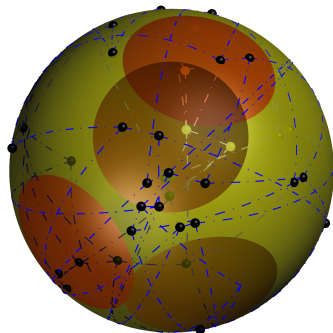
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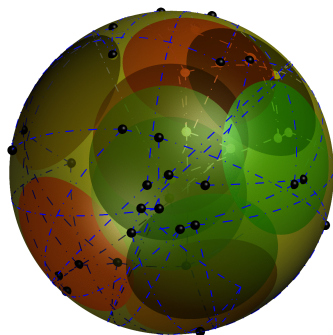
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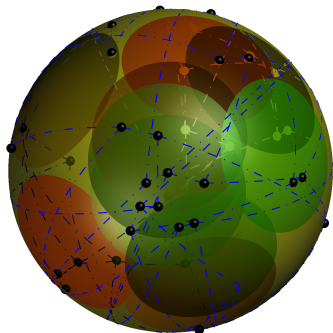


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**Questions?**



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