

Tight bounds for Communication assisted agreement distillation

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Agreement distillation

Alice

Input: $X \in \{0, 1\}^N$

Output: $f_A(X) \in \{0, 1\}^k$

Bob

Input: $Y \in \{0, 1\}^N$

Output: $f_B(Y) \in \{0, 1\}^k$

$(X, Y) \sim \text{BSC}(\varepsilon): \Pr[X_i \neq Y_i] = \varepsilon$

Goal

- $f_A(X)$ uniformly distributed in $\{0, 1\}^k$
- $\Pr[f_A(X) = f_B(Y)]$ close to 1

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Naive protocol: no communication

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Success probability

$$\Pr[f_A(X) = f_B(Y)] = (1 - \varepsilon)^k \approx \exp(-\varepsilon k)$$

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Can we do better?

Yes, a little better (Bogdanov & Mossel 2011)

Alice and Bob can agree with probability least $\approx 2^{-(\epsilon/(1-\epsilon))k}$.

But, no better (Bogdanov & Mossel 2011)

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How much can communication help?

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Input: $X \in \{0, 1\}^N$

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Input: $Y \in \{0, 1\}^N$

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- How many bits must Alice send Bob to ensure agreement with constant probability?
- What is the trade-off between communication and probability of agreement?

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The trade-off

Definition

$C^{\text{BSC}(\varepsilon)}(k, \eta)$ is the minimum number of bits Alice transmits to Bob in a protocol where

- $g_A(X)$ is uniformly distributed in $\{0, 1\}^k$
- $\Pr[g_A(X) = g_B(Y, M)] \geq \eta$

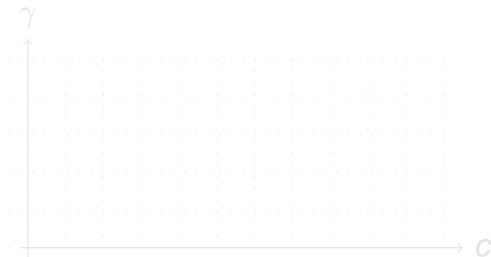
Probability of agreement = $2^{-\gamma k}$

Communication = ck

BM '10: If $c = 0$, then $\gamma = \varepsilon/(1 - \varepsilon)$

This work: If $c = 4\varepsilon(1 - \varepsilon)$, then

$\gamma \rightarrow 0$.



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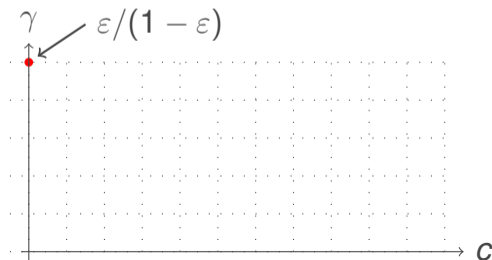
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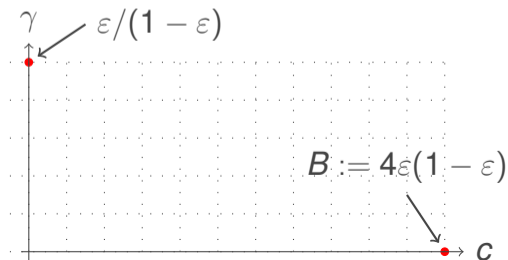
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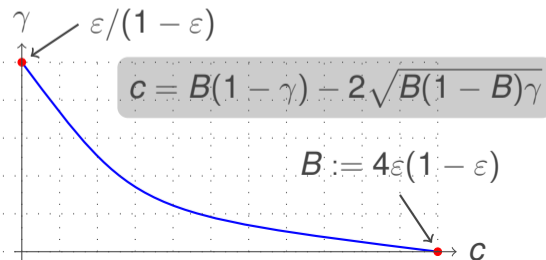
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Related work

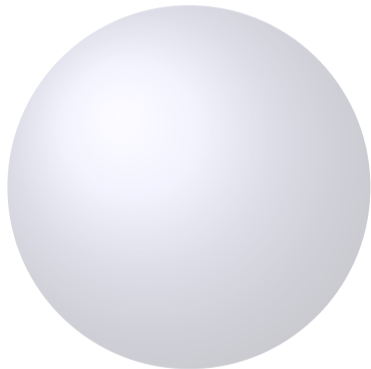
Communication complexity: Canonne, Guruswami, Meka, and Sudan (2015) used capacity-achieving codes to ensure agreement with high probability with $(h(\varepsilon) + o(1))k$ bits of communication.

Information theory: The case $k = 1$ is the subject of a recent conjecture of Courtade and Kumar (2014):

The function $g_A(X) = X_1$ maximizes $I[g_A(X) : Y]$.

Chandar and Tchamkerten (2014) showed that the corresponding conjecture is false for large k .

The protocol of Bogdanov and Mossel

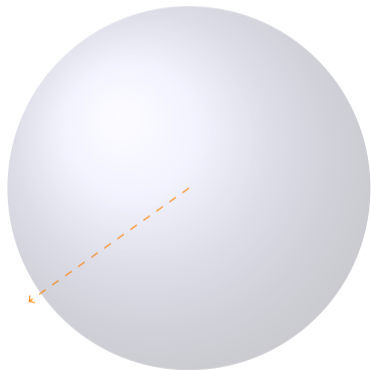


- View $\{+1, -1\}^N$ as points on an N -dimensional sphere.
- Pick 2^k well-separated vectors, labelled by $\{0, 1\}^k$.
- Alice: $f_A(X) =$ closest vector to X
- Bob: $f_B(Y) =$ closest vector to Y

Proof idea

The projections along the various directions are Gaussian and approximately independent.

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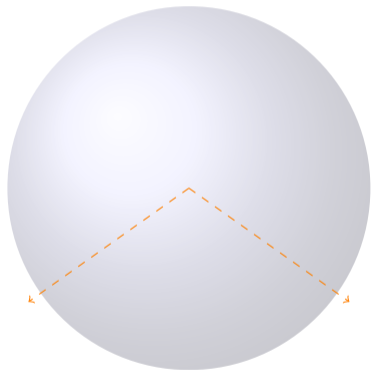


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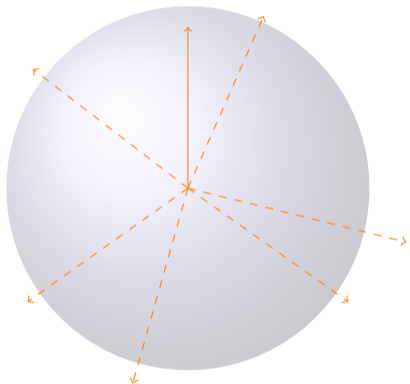


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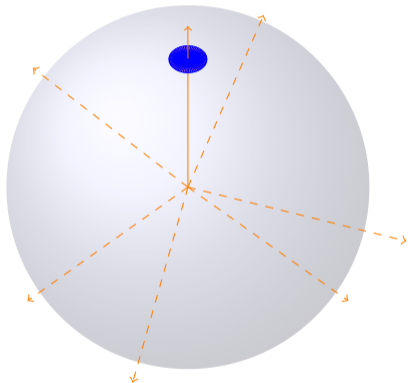


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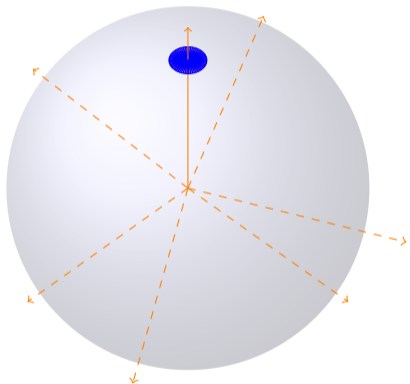


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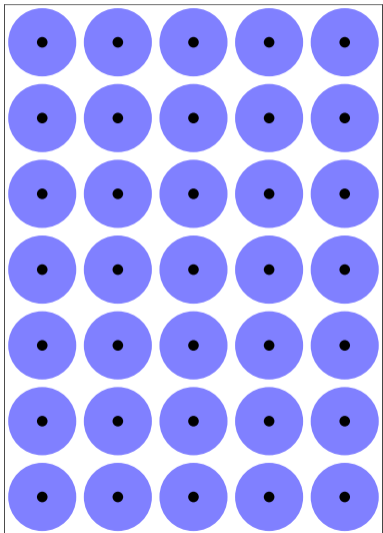


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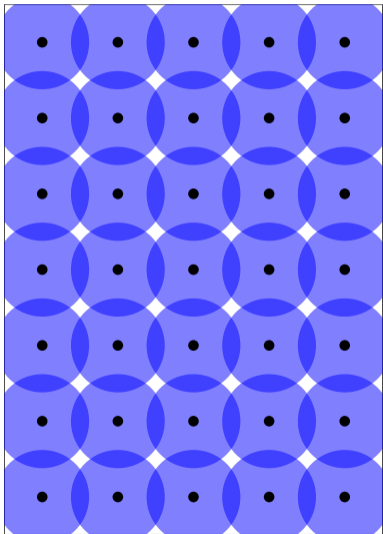
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Alice's view



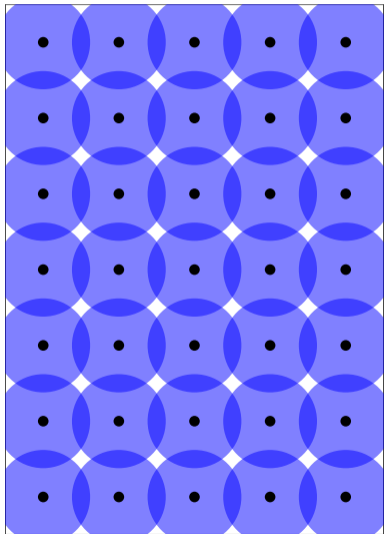
- The ambient space is $\{+1, -1\}^N$.
- The space is partitioned into disks.
- When X falls in a disk, Alice reports the label of its center.
- Each disk has volume $\approx 2^{-k}$.

Bob's view



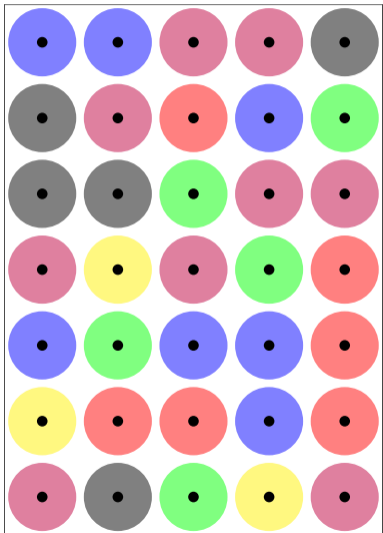
- The disks are bigger and overlap.
- Bogdanov and Mossel '10: *About $2^{-(\epsilon/(1-\epsilon))k}$ of the volume is covered by only one disk.*

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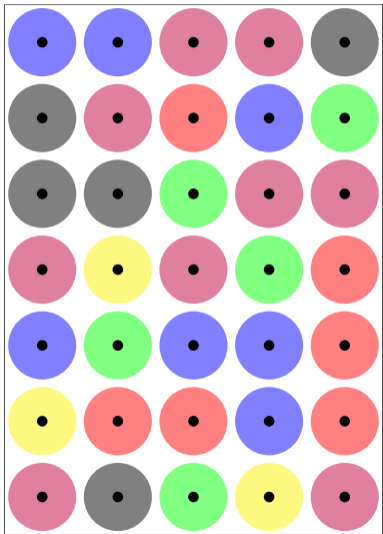
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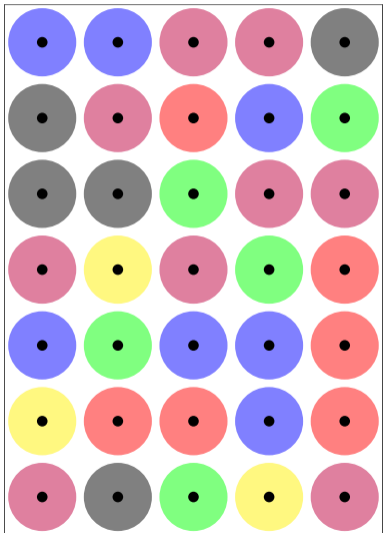
- The space is partitioned into disks.
- The disks are colored using 2^c colors.
- When X falls in a disk, Alice reports the label of its center.
- Alice sends Bob the color of the disk (c bits).

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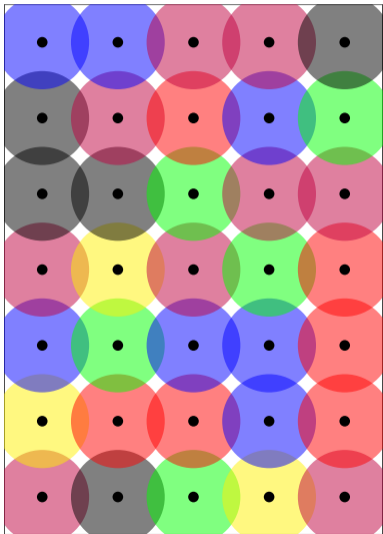
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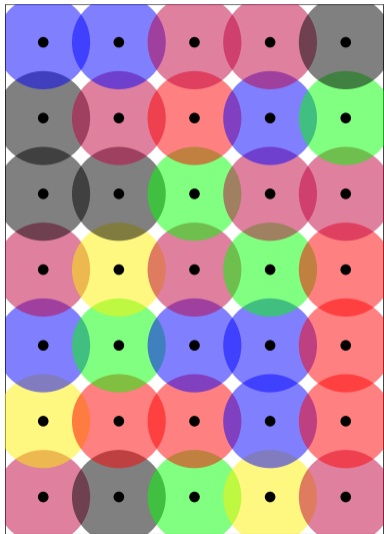
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- Again, the disks are bigger and overlap.
- *But, most points are covered by only one disk of a given color.*
- Bob uniquely identifies the disk (and its center).

How many colors must Alice use?

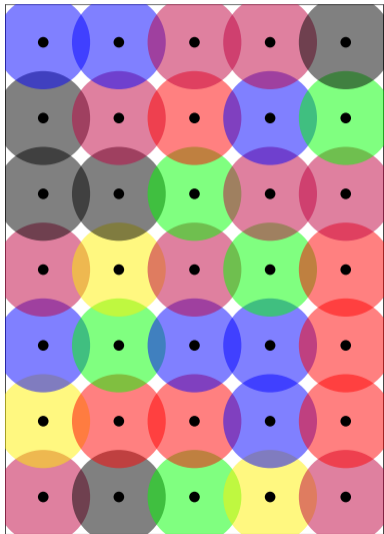
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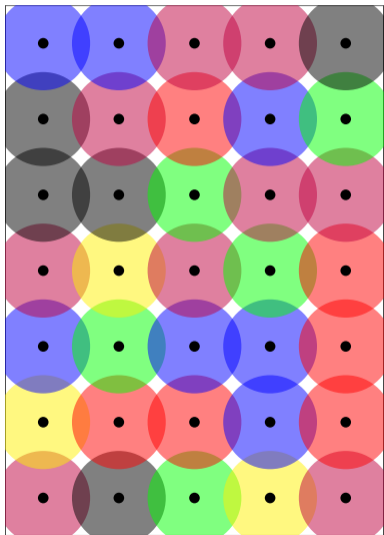
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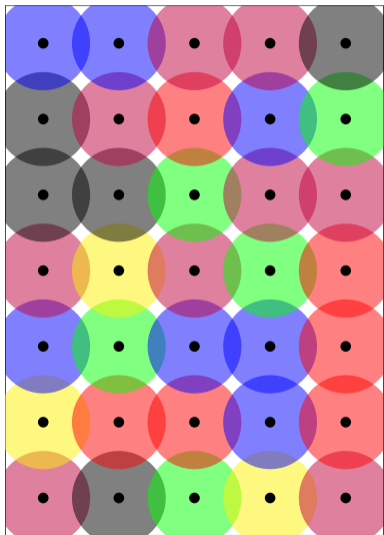
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The calculation

- Suppose Alice chooses $(1, 1, \dots, 1)$
- $\text{vol}(\text{disk}) \approx 2^{-k}$.
- Then for a typical x in Alice's disk, $\text{bias}(x) = t$, where

$$\exp(-t^2) \approx 2^{-k}.$$

- $\text{bias}(y) = (1 - 2\varepsilon)t$.
- Then,
 $\text{vol}(\text{expanded disk}) \approx 2^{-(1-2\varepsilon)^2 k}$.
- So, a typical point is in

$$2^k 2^{-k(1-2\varepsilon)^2} = 2^{4\varepsilon(1-\varepsilon)k}$$

disks.

If Alice uses $\approx 2^{4\varepsilon(1-\varepsilon)k}$ colors, then most points will be covered by at most one disk of any color.

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The lower bound

Theorem

$$C^{\text{BSC}(\varepsilon)}(k, 0.5) \geq 4\varepsilon(1 - \varepsilon)k - o(k).$$

Idea

The “expansion of the discs” seen by Bob is inevitable. This is formalized using a hypercontractivity inequality of the following form. For $f_{\text{Alice}} : \{+1, -1\}^n \rightarrow \mathbb{R}$, let $f_{\text{Bob}}(y) := \mathbb{E}[f_{\text{Alice}}(X) | Y = y]$.

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$$\|f_{\text{Bob}}\|_q \leq \|f_{\text{Alice}}\|_p,$$

where for $\alpha, \beta : \{+1, -1\}^N \rightarrow \mathbb{R}$,

$$\|\alpha\|_p = \mathbb{E}_X[|\alpha(X)|^p]^{1/p}$$

$$\|\beta\|_q = \mathbb{E}_Y[|\beta(Y)|^q]^{1/q}.$$

The analysis

- Suppose Bob receives y .
- Let $\beta(z|y) = \Pr[g_A(X) = z | Y = y]$.
- Without a message, the best strategy for Bob is to output the z for which $\beta(z|y)$ is maximum.

$$\Pr[\text{Success} | Y = y] \leq \max_z \beta(z|y).$$

- Suppose Alice sends c -bit messages; so, there are at most $t = 2^c$ possible transcripts. Then,

$$\Pr[\text{Success} | Y = y] \leq \sum_{i=1}^{2^c} \beta(z_i|y),$$

where $z_1, z_2, \dots, z_t \in \{0, 1\}^k$ give the top t values for $\beta(z|y)$.

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The final bound

Claim

$$\Pr[\text{Success}] \leq \left(\sum_z \mathbb{E}_Y [\beta(z|Y)^q] \right)^{1/q} \cdot t^{1-1/q}.$$

- Using the hypercontractivity inequality with $q = 1 + \delta$ (so, $p = 1 + (1 - 2\varepsilon)^2\delta$), we obtain

$$t \geq \Pr[\text{Success}]^{(1+\delta)/\delta} \cdot 2^{4\varepsilon(1-\varepsilon)k/(1+(1-2\varepsilon)^2\delta)}.$$

- Set $\Pr[\text{Success}] = 2^{-\gamma k}$.
Choose $\delta > 0$ optimally for each choice of γ .

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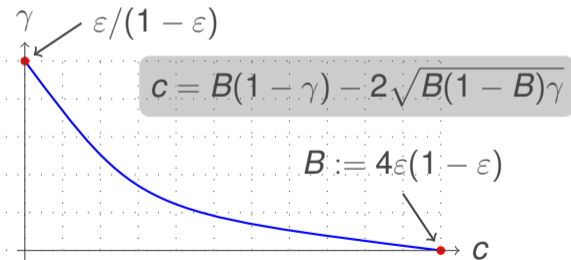
$$t \geq \Pr[\text{Success}]^{(1+\delta)/\delta} \cdot 2^{4\varepsilon(1-\varepsilon)k/(1+(1-2\varepsilon)^2\delta)}.$$

- Set $\Pr[\text{Success}] = 2^{-\gamma k}$.
Choose $\delta > 0$ optimally for each choice of γ .

The result

Probability of agreement = $2^{-\gamma k}$

Communication = ck



The Binary Erasure Channel

Alice

Input: $X \in \{0, 1\}^N$

Output: $f_A(X) \in \{0, 1\}^k$

$(X, Y) \sim \text{BEC}(\epsilon)$: $\Pr[Y_i = \star | X_i = x] = \epsilon$;

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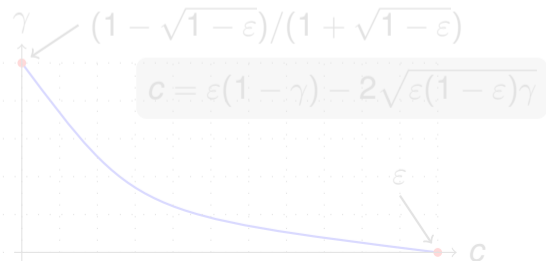
- $c = \epsilon(1 - \gamma) - 2\sqrt{\epsilon(1 - \epsilon)\gamma}$.
- The lower bound is based on a new hypercontractivity inequality due to Nair and Wang (2015).

Bob

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$\Pr[Y_i = x | X_i = x] = 1 - \epsilon$.



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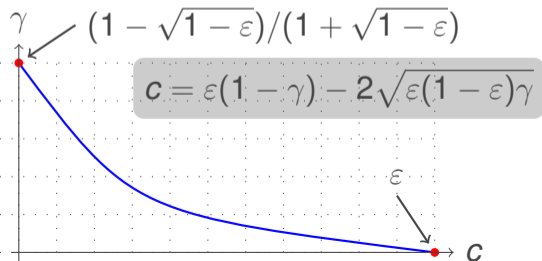
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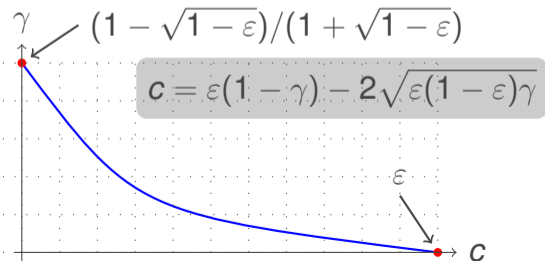
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Open problems

- Our lower bounds apply to communication over multiple rounds, if we assume that Alice's output depends on her input alone. *We do not know if the same lower bound holds without this assumption.*
- We examined the two well-studied channels, $\text{BSC}(\varepsilon)$ and $\text{BEC}(\varepsilon)$, for agreement probability parametrized as $1 - 2^{-\gamma k}$. *We do not know if a general bound applicable to all channels can be stated in terms of some information-theoretic parameter of the channel.* For agreement close to 1 (error close to zero), the works of Zhao & Chia (2011) and Anantharam *et al.* (2013) address this question.

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