

Representations of Monotone Boolean Functions by Linear Programs

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MLP Gates

Weak MLP Gates

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Strong MLP Gates

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Definition (MLP-Circuit Representation)

We say that an MLP circuit C represents a partial Boolean function $F : \{0, 1\}^n \rightarrow \{0, 1, *\}$ if the following conditions are satisfied for each $a \in \{0, 1\}^n$.

- 1 $C(a) > 0$ if $F(a) = 1$.
- 2 $C(a) \leq 0$ if $F(a) = 0$.

Weak MLP gates vs Monotone Boolean Circuits

Theorem

*Let $F : \{0, 1\}^n \rightarrow \{0, 1, *\}$ be a partial Boolean function, and let C be a Boolean circuit of size s representing F . Then for any weak type τ , F can be sharply represented by an MLP gate of type τ and size $O(s)$.*

Weak MLP gates vs Monotone Boolean Circuits

- 1 Let $BPM_n : \{0, 1\}^{n^2} \rightarrow \{0, 1\}$ be the Boolean function that evaluates to 1 on an input $p \in \{0, 1\}^{n^2}$ if and only if p represents a bipartite graph with a perfect matching.
- 2 The Boolean function $BPM_n : \{0, 1\}^{n^2} \rightarrow \{0, 1\}$ can be represented by a MAX-RIGHT MLP gate of size $n^{O(1)}$.
- 3 Monotone Boolean Circuits computing BPM_n must have size $n^{\Omega(\log n)}$ (Razborov 1985).
- 4 Corollary: MAX-RIGHT MLP gates cannot be polynomially simulated by monotone Boolean circuits.
- 5 The gap between the complexity of MAX-RIGHT MLP gates and the complexity of Boolean formulas computing the BPM_n function is even exponential, since Raz and Wigderson have shown a linear lower-bound on the depth of monotone Boolean circuits computing BPM_n (Raz-Wigderson 1992).

Monotone Span Programs

- 1 Monotone span programs (MSP) were introduced by Karchmer and Wigderson (Karchmer-Wigderson 1993).
- 2 Such a program, which is defined over an arbitrary field \mathbb{F} , is specified by a vector $c \in \mathbb{F}^k$ and a labeled matrix $A^\rho = (A, \rho)$ where
 - 1 A is a matrix in $\mathbb{F}^{m \times k}$,
 - 2 $\rho : \{1, \dots, m\} \rightarrow \{p_1, \dots, p_n, *\}$ labels rows in A with variables in p_i or with the symbol $*$ (meaning that the row is unlabeled).
- 3 For an assignment $p := w$, let $A_{\langle w \rangle}^\rho$ be the matrix obtained from A by deleting all rows labeled with variables which are set to 0.

Monotone Span Programs

A span program (A^ρ, c) represents a partial Boolean function $F : \{0, 1\}^n \rightarrow \{0, 1, *\}$ if the following conditions are satisfied for each $w \in \{0, 1\}^n$.

$$F(w) = \begin{cases} 1 & \Rightarrow \exists y, y^T A_{\langle w \rangle}^\rho = c^T \\ 0 & \Rightarrow \neg \exists y, y^T A_{\langle w \rangle}^\rho = c^T \end{cases} \quad (1)$$

Theorem

Let $F : \{0, 1\}^n \rightarrow \{0, 1\}$ be a Boolean function. If F can be represented by an MSP of size s over the reals, then F can be represented by a MIN-RIGHT MLP gate of size $O(s)$.

- 1 It has been recently shown that there is a family of functions $\text{GEN}_n : \{0, 1\}^n \rightarrow \{0, 1\}$ which can be computed by polynomial-size monotone Boolean circuits but which require monotone span programs over the reals of size $\exp(n^{\Omega(1)})$ (Cook et al. 2016).
- 2 On the other hand, monotone Boolean circuits can be polynomially simulated by weak MLP gates of any type
- 3 In particular, weak MLP gates of size polynomial in n can represent the function $\text{GEN}_n : \{0, 1\}^n \rightarrow \{0, 1\}$. Therefore, we have the following corollary.
- 4 Corollary: Weak MLP gates cannot be polynomially simulated by monotone span programs over the reals.

Lovás-Schrijver Proof System

Lovás-Schrijver Proof System

A method to construct certificates of unsatisfiability (proofs) for sets of linear inequalities / CNF formulas.

- 1 Translate clauses into inequalities in the obvious way.
- 2 $x_j \rightarrow x_i$
- 3 $\bar{x}_i \rightarrow (1 - x_i)$
- 4 $(x_1 \vee \bar{x}_2 \vee x_3) \rightarrow x_1 + (1 - x_2) + x_3 \geq 1.$

Lovás-Schrijver Proof System

- Axioms:

- 1 $0 \geq 0, 1 \geq 0, 1 \geq 1$
- 2 $0 \leq p_j \leq 1$
- 3 $p_i^2 - p_i = 0$ (integrality).

- Rules:

- 1 *positive linear combinations of linear and quadratic inequalities*
- 2 *multiplication:* given a linear inequality $\sum_i c_i p_i - d \geq 0$, and a variable p_j , derive

$$p_j \left(\sum_i c_i p_i - d \right) \geq 0 \quad \text{and} \quad (1 - p_j) \left(\sum_i c_i p_i - d \right) \geq 0.$$

- 1 A proof Π of an inequality $\sum_i c_i p_i - d \geq 0$ from Φ is a sequence of inequalities such that every inequality in the sequence is either an element of Φ or is derived from previous ones using some LS rule.
- 2 We say that Π is a refutation of the set of inequalities Φ , if the last inequality is $-d \geq 0$ for some $d > 0$.
- 3 The LS proof system is implicational complete. This means that if an inequality $\sum_i c_i p_i - d \geq 0$ is semantically implied by an initial set of inequalities Φ , then $\sum_i c_i p_i - d \geq 0$ can be derived from Φ by the application of a sequence of LS-rules (Lovasz-Schrijver 1991).

Monotone Feasible Interpolation Theorem For LS

- 1 Let $\Phi(p, q) \cup \Gamma(p, r)$ be an unsatisfiable set of inequalities such that the variables $p = (p_1, \dots, p_n)$ occur in Φ only with negative coefficients.
- 2 Let Π be an *LS* refutation of $\Phi(p, q) \cup \Gamma(p, r)$.
- 3 Then one can construct an MLP circuit C containing only MAX MLP gates which represents a Boolean function $F : \{0, 1\}^n \rightarrow \{0, 1\}$ such that for each $a \in \{0, 1\}^n$,
 - 1 if $F(a) = 1$, then $\Phi(a, q)$ is unsatisfiable,
 - 2 if $F(a) = 0$, then $\Gamma(a, r)$ is unsatisfiable,
- 4 Additionally, the size of the circuit C is polynomial in the size of Π .

Monotone Feasible Interpolation: Who Cares?

- 1 Resolution: monotone boolean circuits (Krajicek 1997) .
- 2 Cutting Planes: monotone *real* circuits (Pudlak 1997). Monotone real circuits are circuits with Boolean inputs and outputs, but whose gates are allowed to be arbitrary 2-input functions over the reals.
- 3 Razborov's lower bound on the clique function has been generalized to monotone real circuits (Pudlak 1997, Cook-Haken 1999).
- 4 Nullstellensatz: Monotone Span Programs (Pudlak Sgall 1998).

Framework for proving lower bounds for proof systems

- Pick a monotone model of computation \mathcal{M} .
- Show that refutations of $\Phi(p, q) \cup \Gamma(p, r)$ can be efficiently translated into monotone \mathcal{M} -circuits which identify which of $\Phi(p, q)$ or $\Gamma(p, r)$ is unsatisfiable.
- Exhibit a family of formulas $\hat{\Phi}(p, q) \cup \hat{\Gamma}(p, q)$ requiring large \mathcal{M} -circuits to decide whether $\hat{\Phi}$ or $\hat{\Gamma}$ is unsatisfiable.
- Then refutations of the corresponding formula must be large.

- 1 Our interpolation theorem for LS proof systems is stated in terms of strong MLP gates.
- 2 Strong MLP gates can compute quadratic functions!
- 3 Lower bounds seem to be out of reach.
- 4 Better chance: Weak MLP gates.
- 5 Size of MLP gates computing monotone functions has some relations with the field of extended formulations.

Theorem (From Circuits to Gates)

Let C be an MLP circuit of size s where all gates in C are weak MLP gates of type τ . Then there is an MLP gate ℓ_C of type τ and size $O(s)$ such that for each $a \in \mathbb{R}^n$ for which $C(a)$ is defined, $\ell_C(a) = C(a)$.

Monotone Feasible Interpolation for Mixed LS

- 1 Let $\Phi(p, q) \cup \Gamma(p, r)$ be a set of inequalities where p, q range over 0s and 1s, r range over reals, and the common variables $p = (p_1, \dots, p_n)$ occur in Φ only with negative coefficients.
- 2 Let Π be an LS-refutation of $\Phi(p, q) \cup \Gamma(p, r)$.
- 3 Then there exists a MAX-LEFT MLP gate ℓ that represents a Boolean function $F : \{0, 1\}^n \rightarrow \{0, 1\}$ such that for every $a \in \{0, 1\}^n$,
 - 1 if $F(a) = 1$, then $\Phi(a, q)$ is unsatisfiable, and
 - 2 if $F(a) = 0$, then $\Gamma(a, r)$ is unsatisfiable,
- 4 Additionally, the size of the MLP gate ℓ is polynomial in the size of Π .

Relation with Other Proof Systems

LS vs Other Proof Systems

1 Resolution

$$1 \quad (A \vee x) \wedge (B \vee \bar{x}) \rightarrow A \vee B$$

2 Cutting Planes

- 1 Positive linear combinations of inequalities.
- 2 Rounding rule: If c_i are integers, then from $\sum c_i p_i \geq d$ derive $\sum c_i p_i \geq \lceil d \rceil$.

LS vs Resolution

- 1 The LS proof system is strictly stronger than Resolution.
 - 1 Resolution proofs can be simulated by LS proofs with a linear blow up in size.
 - 2 Pigeonhole principle requires resolution proofs of exponential size (Haken 1985).
 - 3 Pigeonhole principle has LS proofs of polynomial size.

LS vs Cutting Planes

- 1 Problems stated in the 1990's.
- 2 Determine whether LS proofs can be superpolynomially more concise than Cutting Planes Proofs. (Solved in this work.)
- 3 Determine whether cutting-planes proofs can be superpolynomially more concise than LS proofs. (Still Open)

CP does not polynomially simulate LS

- 1 Cutting plane proofs can be interpolated in terms of monotone real circuits (Pudlák 1997)
- 2 Monotone real circuit separating unbalanced graphs on n vertices from perfect matchings must have size $n^{\Omega(\log n)}$ (Fu 1998, by a generalization of Razborov's lower bound for monotone Boolean circuits).
- 3 Therefore Unbalanced Graphs vs Perfect Matching Inequalities require superpolynomial cutting plane proofs. (Fu 1998)
- 4 Unbalanced Graphs vs Perfect Matching Inequalities have short Mixed LS proofs. (This work)
- 5 Bonus: By our monotone interpolation theorem for mixed LS, a single weak MLP gate can separate unbalanced graphs from perfect matchings.
- 6 Therefore weak MLP gates can be superpolynomially stronger than monotone real circuits.

Open Problems

- 1 Prove superpolynomial lower bounds the size of weak MLP gates.
- 2 What if we make reasonable restrictions on the allowed gates?
Examples: Bound on coefficients, or on the number of internal variable of the MLP gate.
- 3 Strengthen connections with extended formulations.
- 4 Show that monotone real circuits can be superpolynomially more concise than weak MLP gates. This would show that the two models are incomparable.
- 5 Monotone semidefinite programming gates? Which proofs systems can be interpolated by this model?

Thank you!